

Addition of Angular Momentum

$$\vec{J}_1 \quad |j_1, m_1\rangle \quad m_1 = -j_1, \dots, j_1$$

$$\vec{J}_2 \quad |j_2, m_2\rangle \quad m_2 = -j_2, \dots, j_2$$

$$H_j = \sum_{j_1} H_j^{(j_1)}$$

$$H_1^{(\vec{j}_1)} = \{|j_1, m_1\rangle\}$$

$$H_2^{(\vec{j}_2)} = \{|j_2, m_2\rangle\}$$

Define: $\vec{J} = \vec{J}_1 + \vec{J}_2 = \vec{J}_1 \otimes \mathbb{1} + \mathbb{1} \otimes \vec{J}_2$

↑ acts on vectors in $H_1^{(j_1)} \otimes H_2^{(j_2)}$

Uncoupled basis $|j_1, j_2, m_1, m_2\rangle = |j_1, m_1\rangle \otimes |j_2, m_2\rangle$

$$\begin{pmatrix} J_1^2 \\ J_{1z} \\ J_2^2 \\ J_{2z} \end{pmatrix} \left(|j_1, m_1\rangle \otimes |j_2, m_2\rangle \right) = \begin{pmatrix} \hbar^2 j_1 (j_1 + 1) \\ m_1 \hbar \\ \hbar^2 j_2 (j_2 + 1) \\ m_2 \hbar \end{pmatrix} \left(|j_1, m_1\rangle \otimes |j_2, m_2\rangle \right)$$

Complete set of commuting observables

This makes it perfect to
use it to define state basis

However we can also think about our \vec{J} in terms of \vec{J} operators:

$$\vec{J}^2 = (\vec{J}_1 \otimes \mathbb{1} + \mathbb{1} \otimes \vec{J}_2)(\vec{J}_1 \otimes \mathbb{1} + \mathbb{1} \otimes \vec{J}_2)$$

$$\vec{J}^2 = J_1^2 \otimes \mathbb{1} + \mathbb{1} \otimes J_2^2 + \sum_k J_{1k} \otimes J_{2k} \Rightarrow [J_{1z}, \vec{J}^2] \neq 0$$

$$[J_{2z}, \vec{J}^2] \neq 0$$

$$\text{but } [J_z, \vec{J}^2] = 0$$

another commuting observables: $\{J_1^2, J_2^2, \vec{J}^2, J_z\}$

↑ natural basis $|j_1 j_2, j, m\rangle \equiv |j, m\rangle$
(of eigenvectors)

↳ Coupling Basis

Both basis are orthonormal \rightarrow they both come from Hermitian operators

Orthonormal: $\sum_{j_1, j_2} \sum_{m_1, m_2} |\langle j_1 j_2, m_1, m_2 | \rangle \langle j_1 j_2, m_1, m_2 | = \mathbb{1} \text{ on } H_1 \otimes H_2 \rightsquigarrow$ for any given j_1, j_2 or (\vec{j}_1, \vec{j}_2)

Anyhow we could also think about smaller Hilbert spaces where we fixed J_1 and J_2 operators.

$$\sum_{m_1 m_2} |j_1 j_2 m_1 m_2\rangle \langle j_1 j_2 m_1 m_2| = 1 \text{ on } H_1^{(J_1)} \otimes H_2^{(J_2)} \quad \begin{array}{l} J_1 \text{ and } J_2 \text{ are} \\ \text{fixed operators} \end{array}$$

Since j_1 and j_2 are fixed values we can use the completeness relation to write one basis in terms of the other

$$\Rightarrow |j_1 j_2 jm\rangle = \sum_{m_1 m_2} |j_1 j_2 m_1 m_2\rangle \langle j_1 j_2 m_1 m_2| j_1 j_2 jm\rangle$$

Clebsch-Gordan Coefficients

$$C(j_1 j_2 j m; m_1 m_2)$$

Properties: 1) Vanish if $m \neq m_1 + m_2$

Proof: $J_z = J_{z1} + J_{z2} \rightarrow (J_z - J_{z1} - J_{z2}) = 0$

$$\langle j_1 j_2 m_1 m_2 | (J_z - J_{z1} - J_{z2}) | j_1 j_2 jm \rangle = 0$$

$$\langle j_1 j_2 m_1 m_2 | \hbar m - \hbar m_1 - \hbar m_2 | j_1 j_2 jm \rangle = 0$$

$$\boxed{(m - m_1 - m_2) \langle j_1 j_2 m_1 m_2 | j_1 j_2 jm \rangle = 0}$$

2) Clebsh coefft vanish unless $|j_1 - j_2| \leq j \leq j_1 + j_2$ → think about \vec{J}_1, \vec{J}_2 as vectors each j occurs once

Uncoupled basis

$$N_j = (2j+1) (2j_2+1) \# \text{ states}$$

or top states

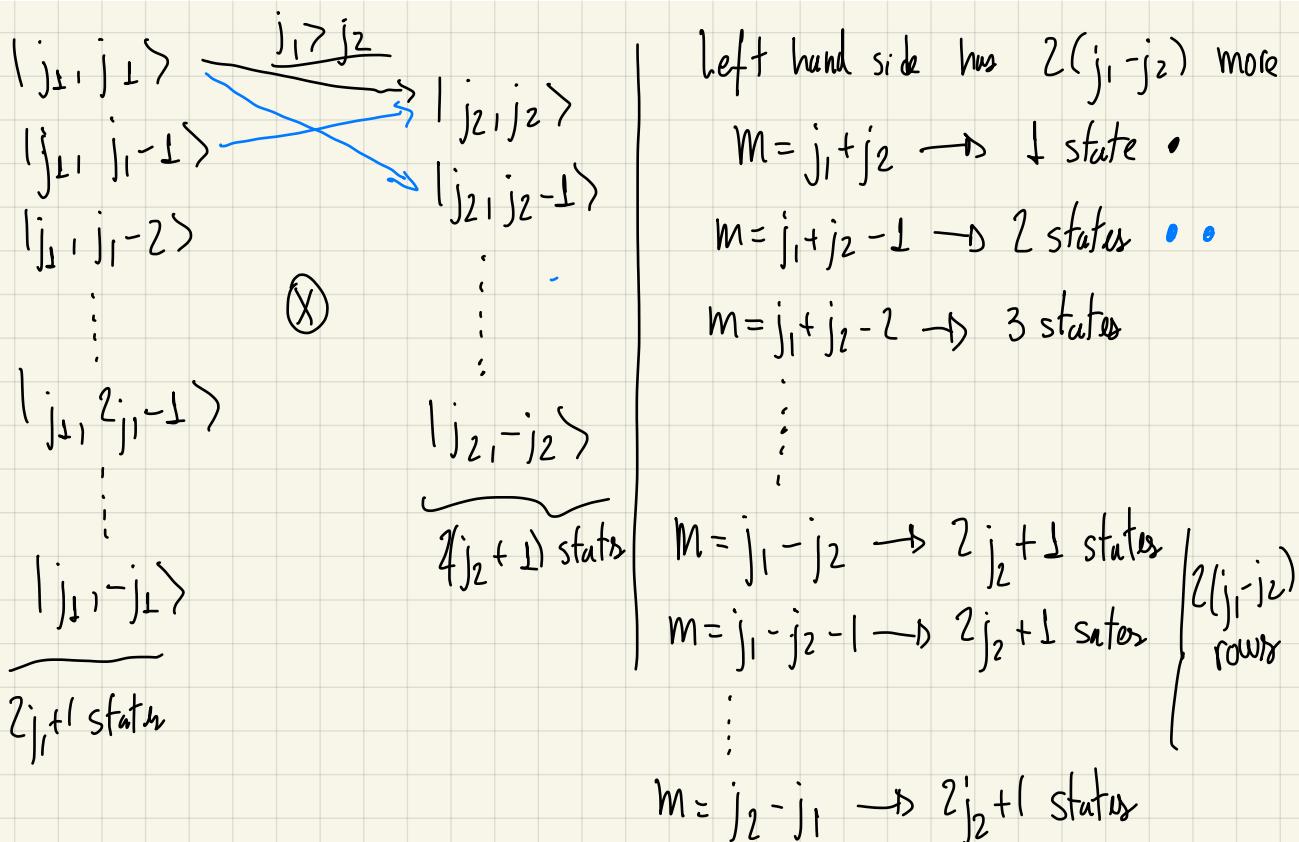
$$|j_1 j_2 j; j_1 + j_2, m = j_1 + j_2\rangle = |j_1 j_2 j; m = j_1, m_2 = j_2\rangle$$

$$\vec{J}^2 = J_1^2 + J_2^2 + 2 J_1 J_2 = J_1^2 + J_2^2 + 2 J_{z1} J_{z2} + J_{z1} + J_{z2} + J_{z1} - J_{z2} +$$

Assume (2) is true

$$\begin{aligned} N_{\text{coupled}} &= \sum_{j=0}^{j_1+j_2} (2j+1) \quad \text{Assume } j_1 \geq j_2 \\ &= \sum_{j=0}^{j_1+j_2} (2j+1) - \sum_{j=0}^{j_1-j_2-1} (2j+1) \\ &= 4j_1 j_2 + 2j_1 + 2j_2 + 1 \\ &= (2j_1+1)(2j_2+1) \quad \text{consistency} \end{aligned}$$

$$\begin{aligned} \vec{J}^2 |j_1 j_2 j; j_1 + j_2, m = j_1 + j_2\rangle &= \hbar^2 (j_1(j_1+1) + j_2(j_2+1)) + 2j_1 j_2 + 0 + 0 |.. \rangle \\ &= \hbar^2 (j_1 + j_2)(j_1 + j_2 + 1) |.. \rangle \end{aligned}$$



\rightsquigarrow forms separated multiplets \rightarrow Different values of j_1, j_2 and consecutively m have states

3-) C_{6j} coeffs can be chosen to be real

with different values of j . The multiplets

4-) Satisfies a recursion relation

are these different states that undergo the same

Value of j

\hookrightarrow Is passive of understanding as
Some level of "degeneracy" in total angular momentum